

**leti**  
cea tech

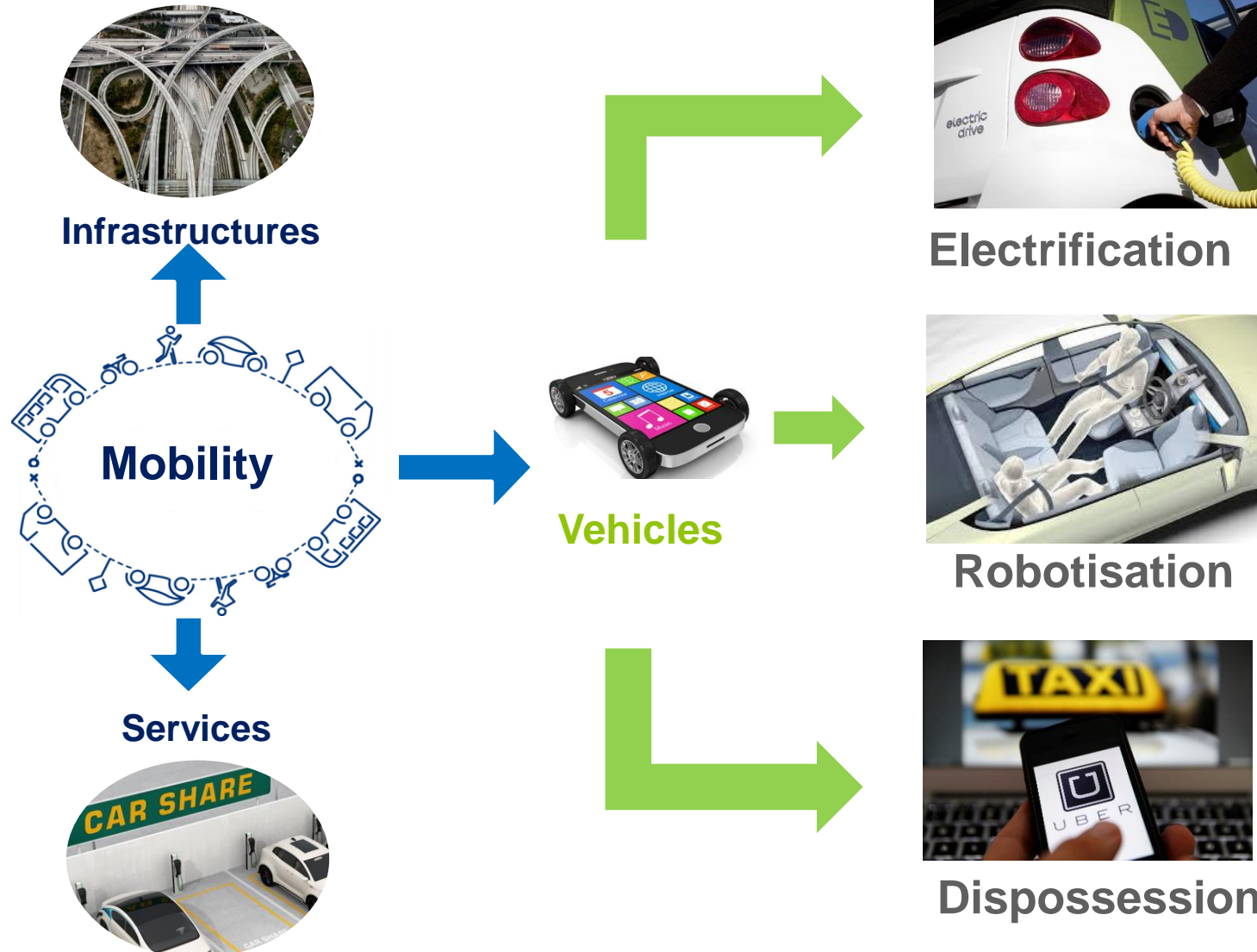


# LETI INNOVATION DAYS

**JULY 4-5, 2018**  
GRENOBLE, FRANCE

**MOBILITY: A NEW ERA FOR THE INDUSTRY**

## A NEW ERA FOR MOBILITY



### BASED ON SEMICONDUCTOR TECHNOLOGY !

- 80% of all core innovation
- Electronics: 50% of vehicle production cost in 2030 (30% in 2015)
- Shorter time gap consumer vs automotive



# GAN POWER ELECTRONICS FOR E-MOBILITY

## From GaN power components...

- Cascode transistors
- Diodes, N.OFF transistors
- Bidirectional N.OFF transistors

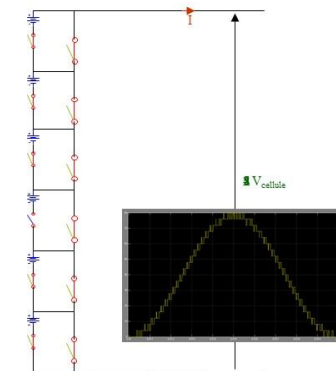
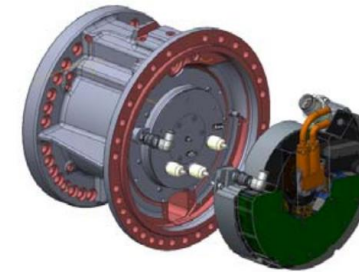


200 mm wafer GaN / Si



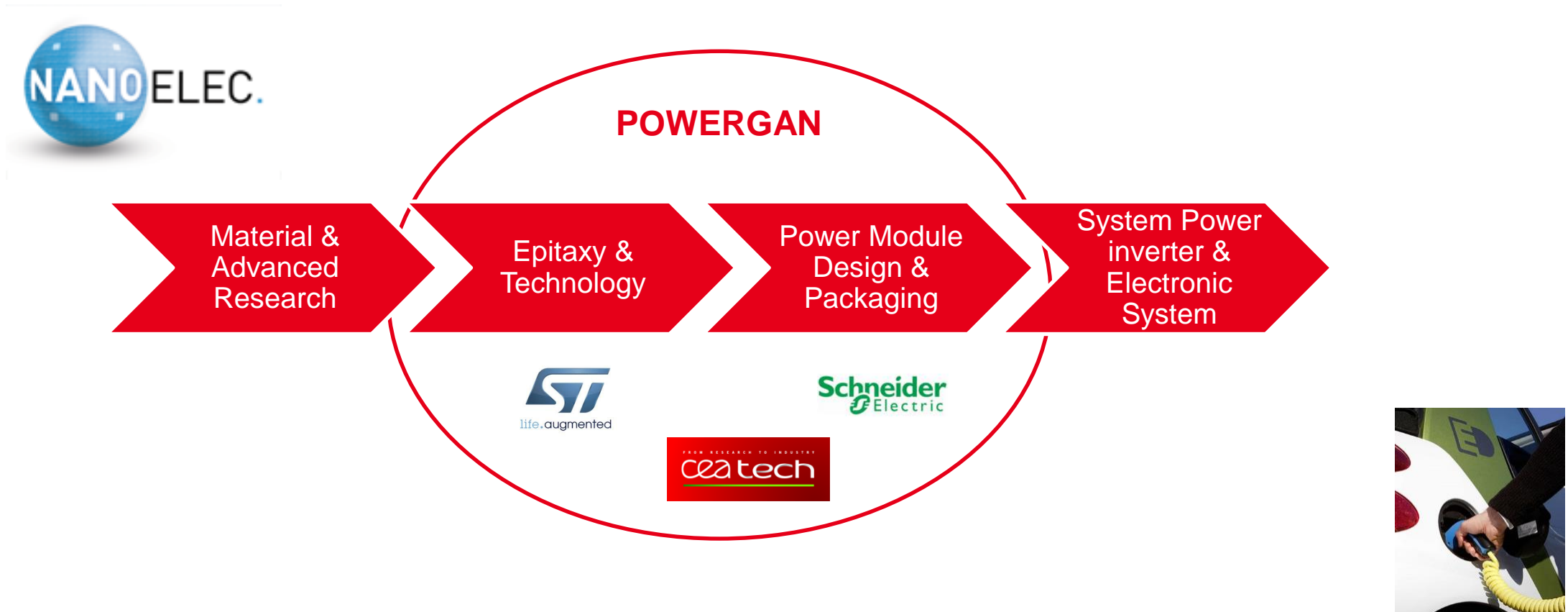
## ...to innovative systems

- GaN to get direct inverters integration in motors
  - New motors architectures
  - Full flexibility in driving
- Disruptive electrical architectures with « all in one » concept
  - Optimized BMS
  - Remove charger and inverter
- GaN to enable bi-directionnal charger
  - Perfect adequation for Smart Grid scenario
  - Conversion capability > 10kW per litre

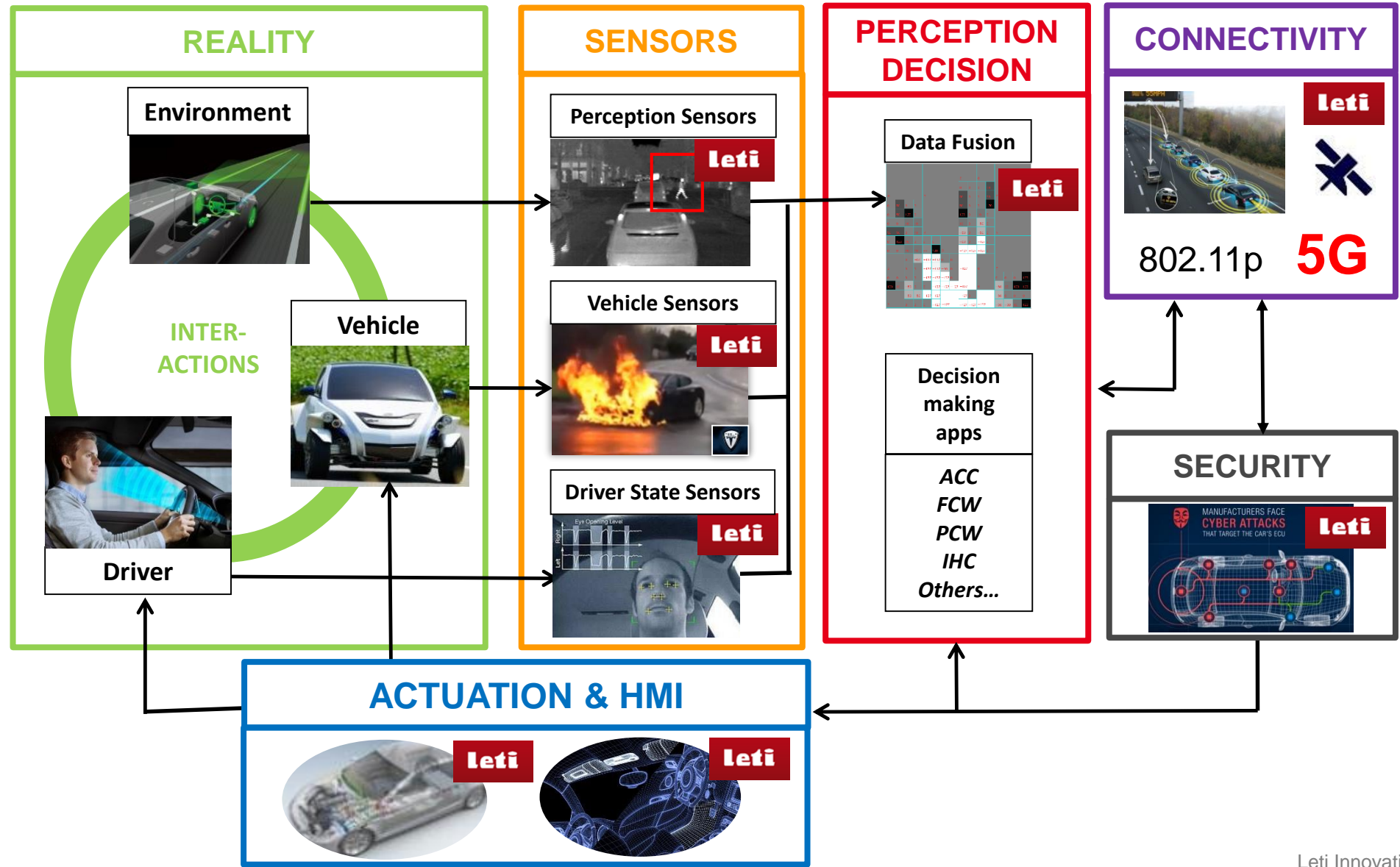


## BUILDING & LEVERAGING ECOSYSTEMS:

**IRT NANOelec POWERGAN:** A French ecosystem platform from GaN/Si power devices to innovative system architectures that will allow major breakthroughs in terms of power converter energy efficiency and power density.



# ROBOTISATION: AUTONOMOUS VEHICLE ARCHITECTURE



**Race to driverless cars**  
Number of interventions per 1,000 miles, Dec 1 2016 to Nov 30 2017 (log scale)\*

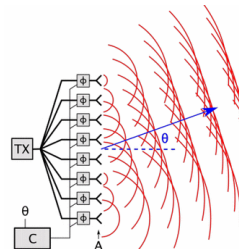
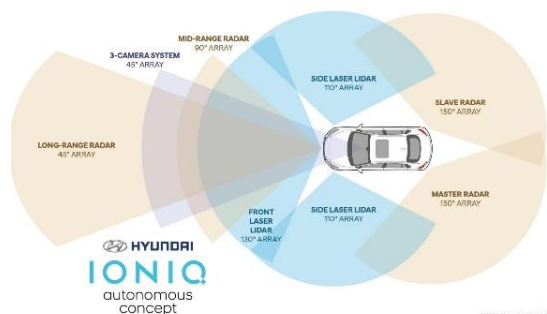
Company	Interventions per 1,000 miles
Waymo	0.2
GM Cruise	0.8
Nissan	4.8
Zoox	6.2
Baidu	21.9
Drive.ai	23.0
Telenav	35.8
Nvidia	102.0
Delphi/Aptiv	122.8
Valeo	374.5
Mercedes	774.1
Bosch	411.3

\* Based on autonomous testing in California

**UBER REVIEWING ARIZONA CRASH**

# SELF-DRIVING VEHICLES WILL NEED IR SENSORS

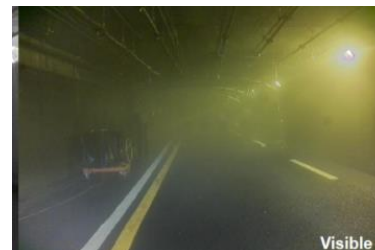
## LIDAR



III-V laser, SOA, PD

- **Cost reduction:**  
Solid state  
Heterogeneous integration
- **Size reduction:**  
Towards LIDAR on chip
- **Higher performance:**  
Lower power: towards smart LIDAR  
Long distance / Low R object detection

## IR CAMERA



Visible



NIR

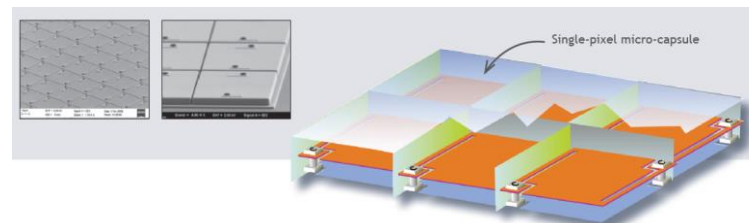


LWIR

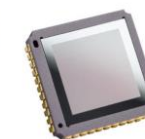


Navigation in bad weather condition requires  
Visible RGB, NIR & Thermal Infrared camera fusion

- **Cost reduction / high volume production:**  
Packaging, CMOS compatible process
- **Smaller Form factor:**  
Pixel size reduction
- **Without compromise on performances:**



Atto320  
320x240 - 12  $\mu\text{m}$   
NETD <60mK  
Operating Temp: -40°C +85°C



# IMPACT OF AI ON PROCESSING REQUIREMENT



State of the art based on GPUs

High-end computing architecture:  
*cost, power consumption, low SIL...*



Requirement of short loop « safety checker»

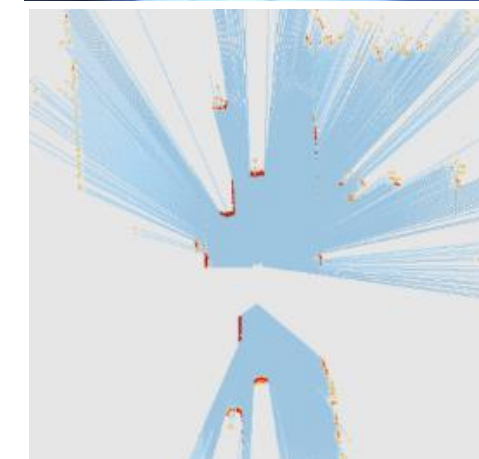
## SigmaFusion

- ✓ **Errorless** computing
- ✓ **Fusion** of 2x Velodyne VLP 16 LIDARs + 1 stereo camera
- ✓ **Bayesian fusion** based on **integer arithmetic**
- ✓ **Compatible w existing automotive HW & high SIL**
- ✓ **3 patents**



## 360Fusion:

- ✓ **low-power 3D fusion embedded in drones**



# Thanks



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